IN THE SPECIFICATION

Kindly cancel the amendments made in the previous submission by applicant to the paragraph starting at page 3, line 27 and to the paragraph starting at page 34, line 21.

Kindly amend the paragraph starting at page 3, line 27, as follows: why again and here?

--Range is divided into range gates, and the FFT is done separately for each range gate, and in parallel for all gates. Each Doppler filter that results belongs to a certain range gate, covers a certain portion of the Doppler spectrum and constitutes a range-Doppler cell, representing a terrain cell/obstacle/object. The process results therefore in a matrix, containing n x m cells, where n is the number of range gates and m is the number of Doppler filters. In principle, azimuth and elevation is found for each cell.--

Kindly amend the paragraph starting page 23, line 21 as follows:

--Fig. 16 shows an example of a skyline contour type display 1600 (see further description of the display below), if ambiguity is not resolved. This "display" shows two contours, an upper contour 1602 and a lower contour 1604. From this display it is not known which of the contours (upper or lower) is the true contour. As an example of this ambiguity, consider a situation in which the FP is pointing below the skyline. In this situation, the true contour on the display is the upper one, and the lower contour is the image, contrary to a simplistic conclusion that might be made by the crew based on the display. Also shown on the display are line of flight symbol 1605, a safety circle 1606 and the flight plane [[1808]] 1608. Of course, not all of these symbols and lines need actually be shown on the display, while other symbols may be added.--